

Development and Characterization of Optical Follower Servo for Photon Calibrator for KAGRA Gravitational Wave Observation

Bin-Hua Hsieh¹,

Yu-Kuang Chu², Sadakazu Haino³, Yuki Inoue^{3,4}, Takaaki Kajita¹,
Nobuyuki Kanda⁵, Takaharu Shishido⁶, Takayuki Tomaru^{4,6},
Satoshi Tsuchida⁵, Takahiro Yamamoto¹, Takaaki Yokozawa¹

1: ICRR, The University of Tokyo

2: National Taiwan Normal University

3: Academia Sinica

4: High Energy Accelerator Research Organization

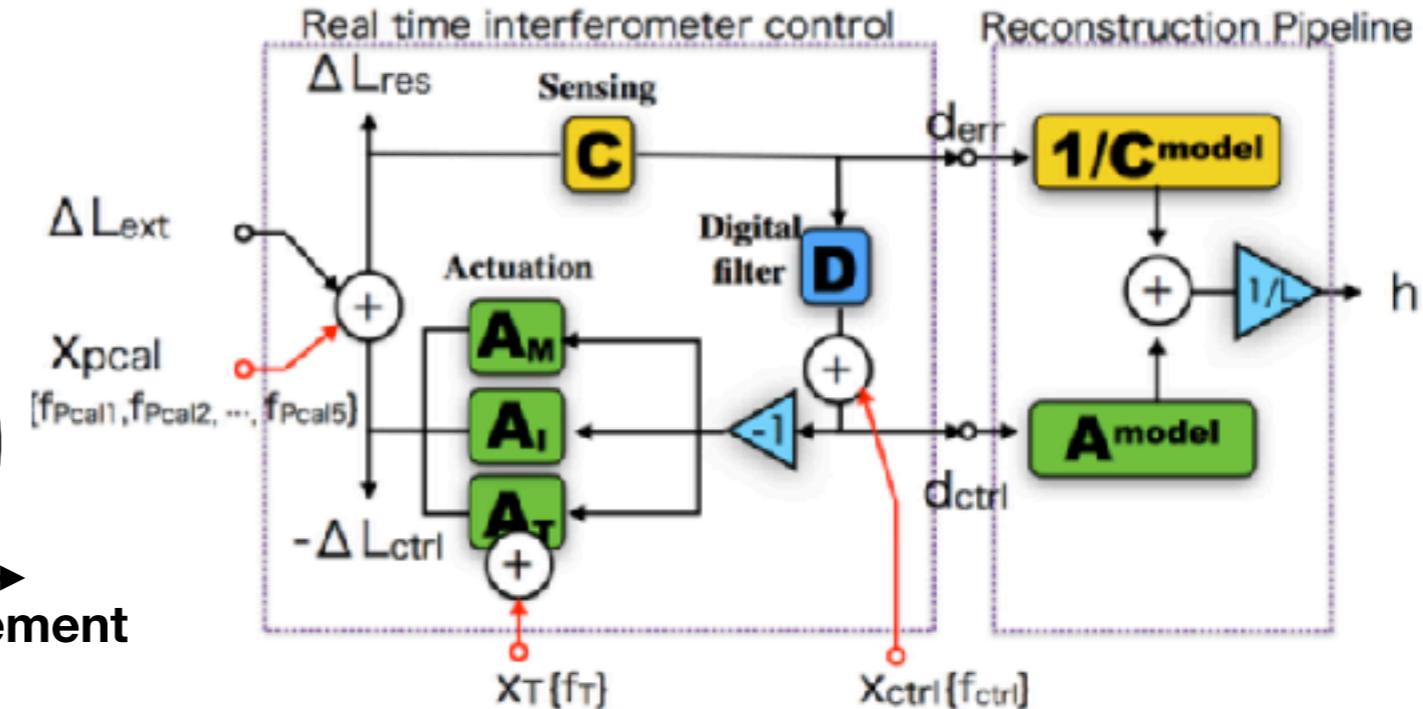
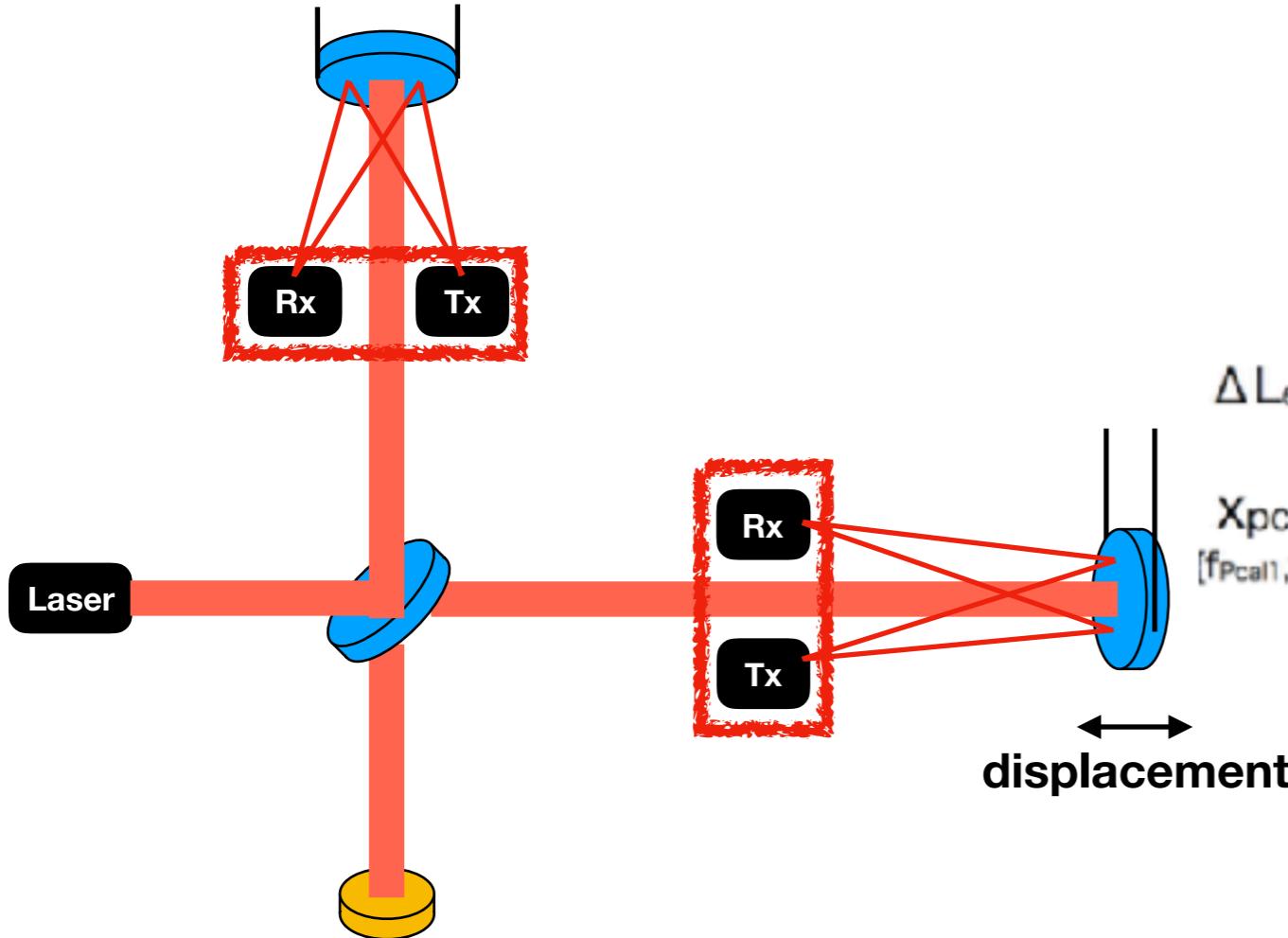
5: Osaka City University

6: SOKENDAI

Outline

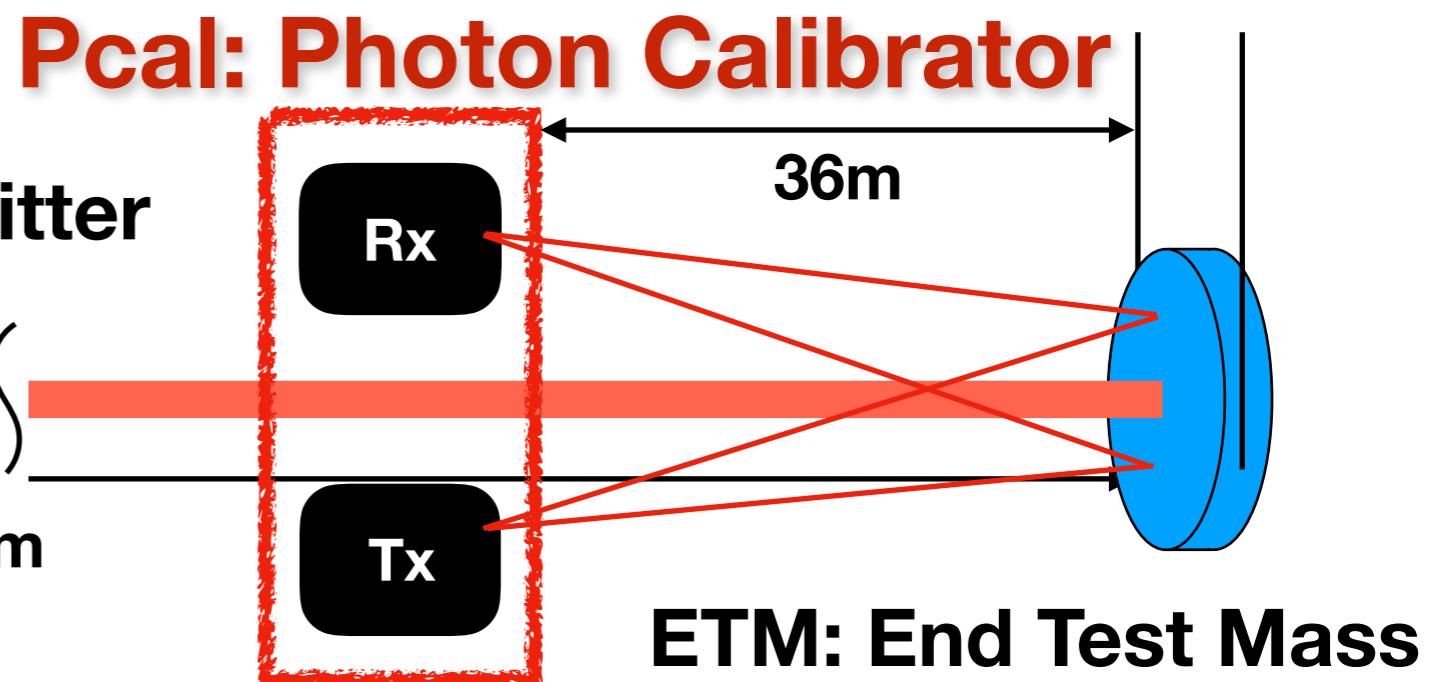
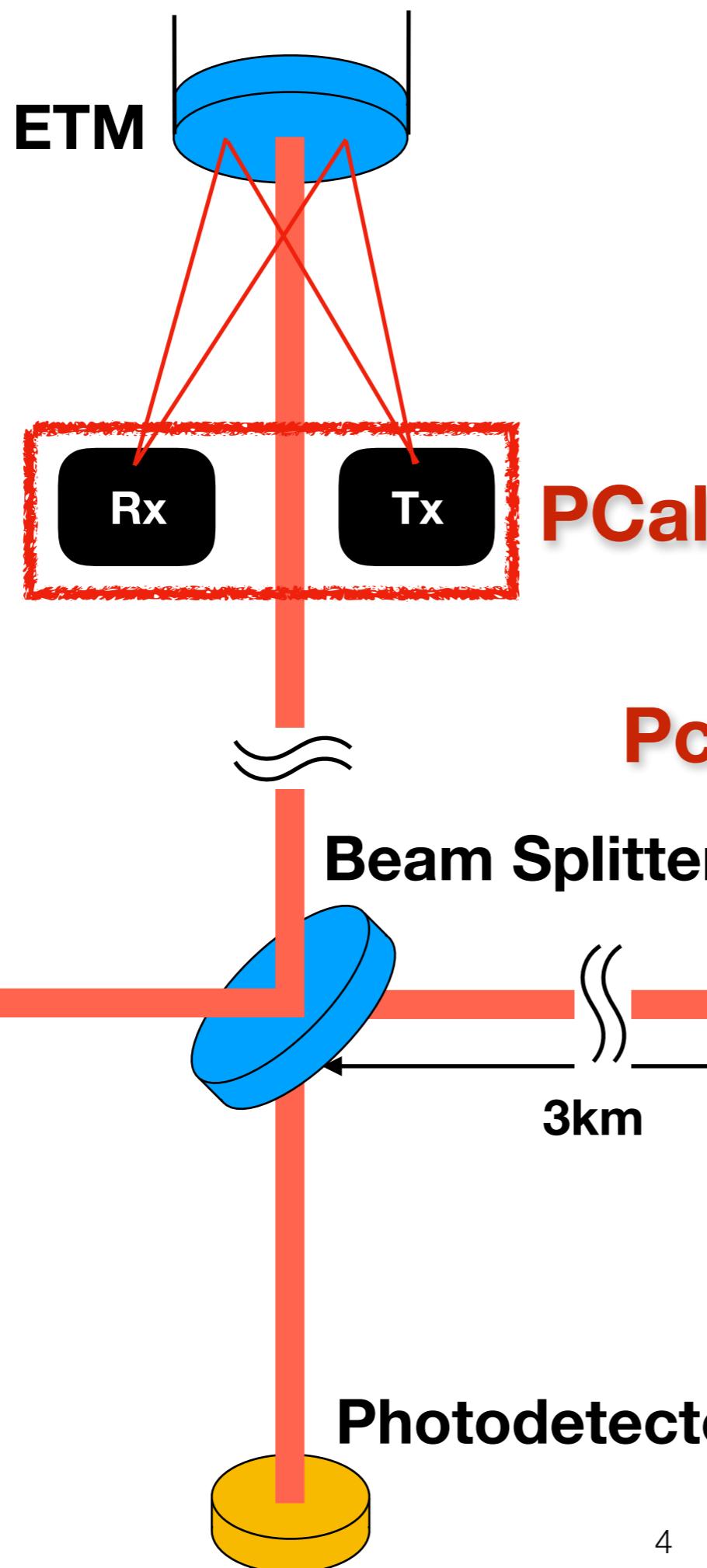
- Overview
- Instruments of Photon Calibrator
- Requirements
- Optical Follower Servo and feedback loop
- Calibration lines
- Summary

Why we need Photon Calibrator?

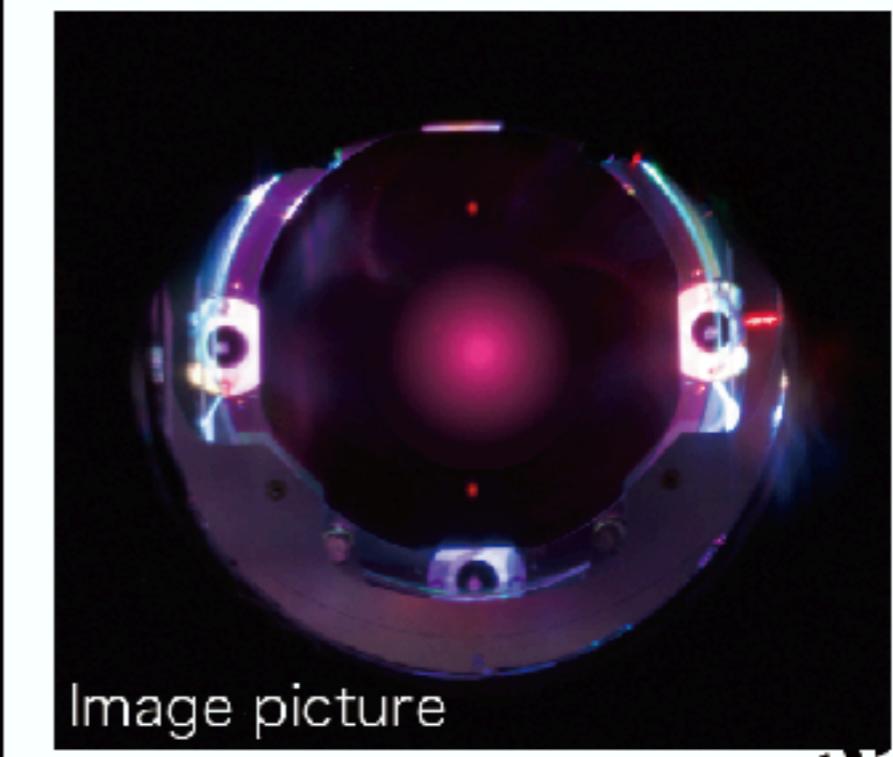
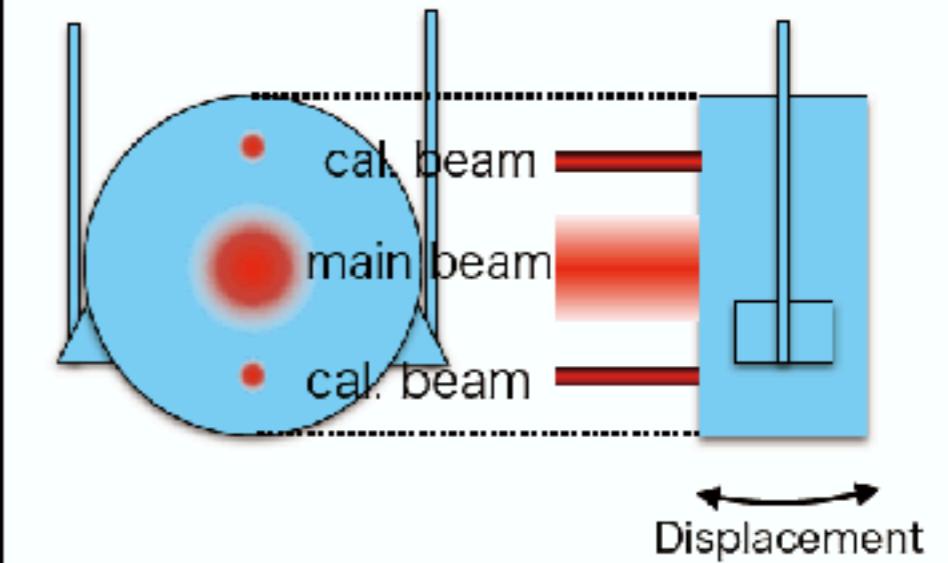
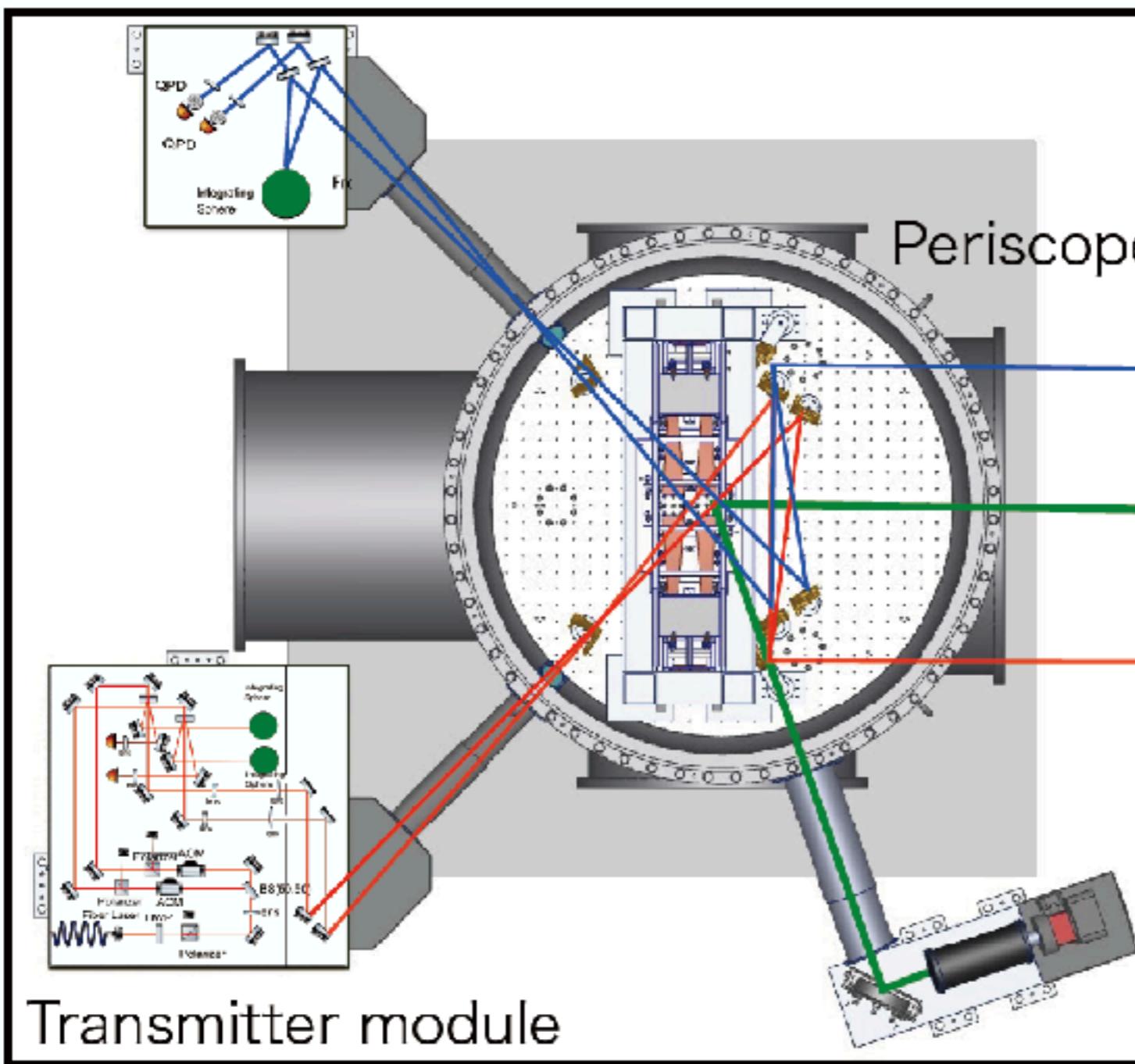


1. Characterize the displacement of mirror
2. Understand the parameter in realtime interferometer control in order to reconstruct the gravitational wave signal.

Where is Photon Calibrator in KAGRA?



Receiver module

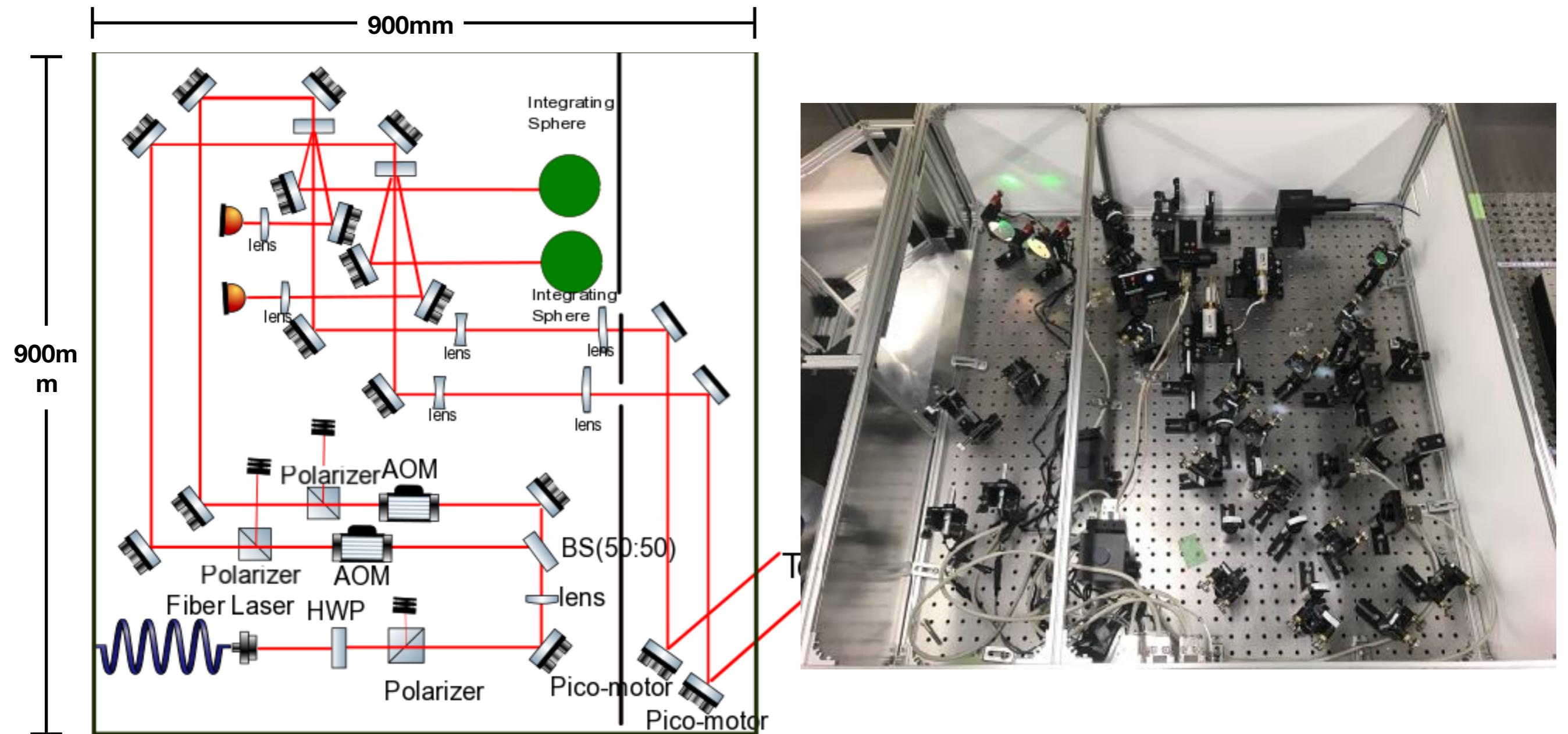


Transmitter module

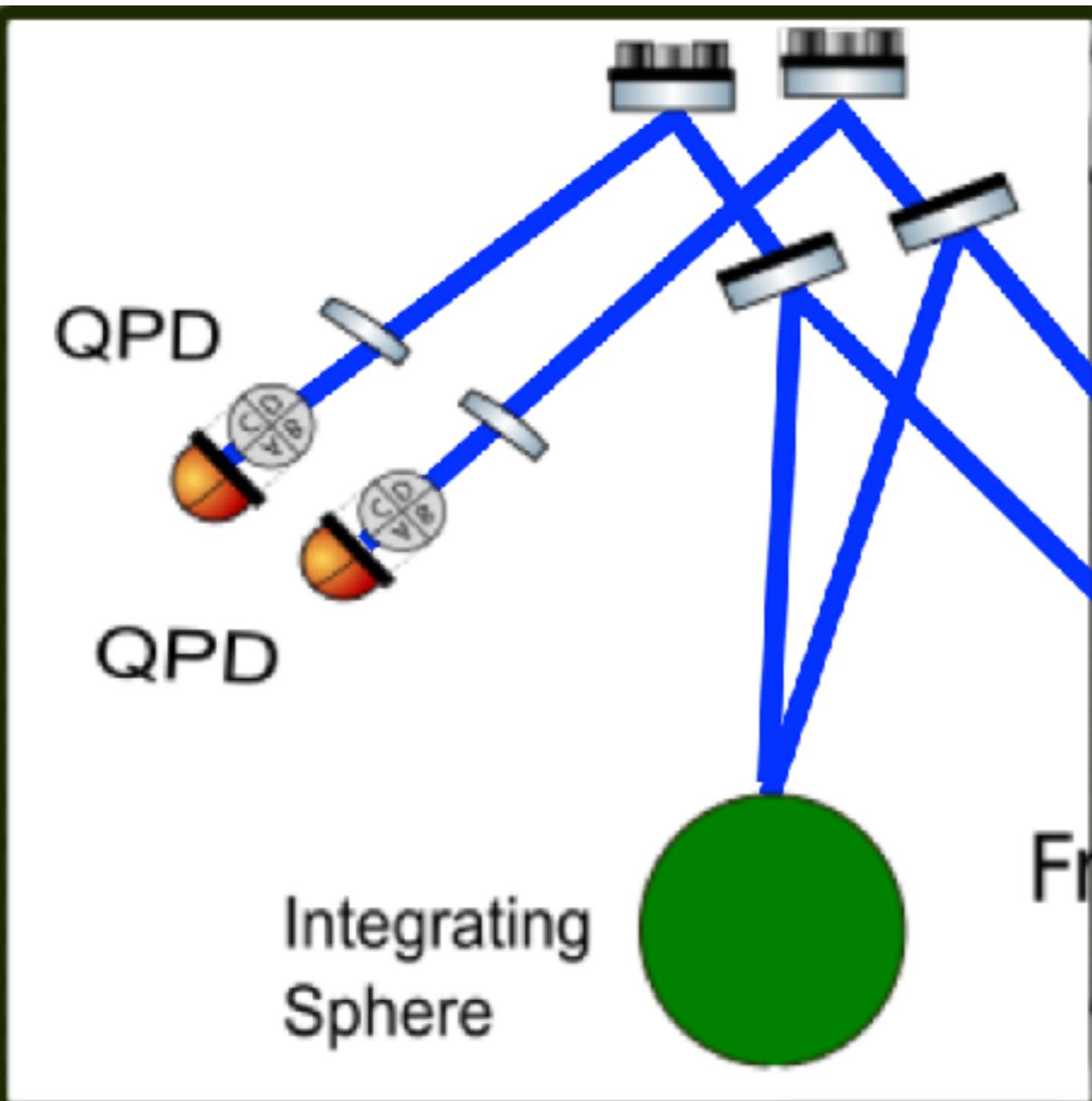
Telephoto camera

36m

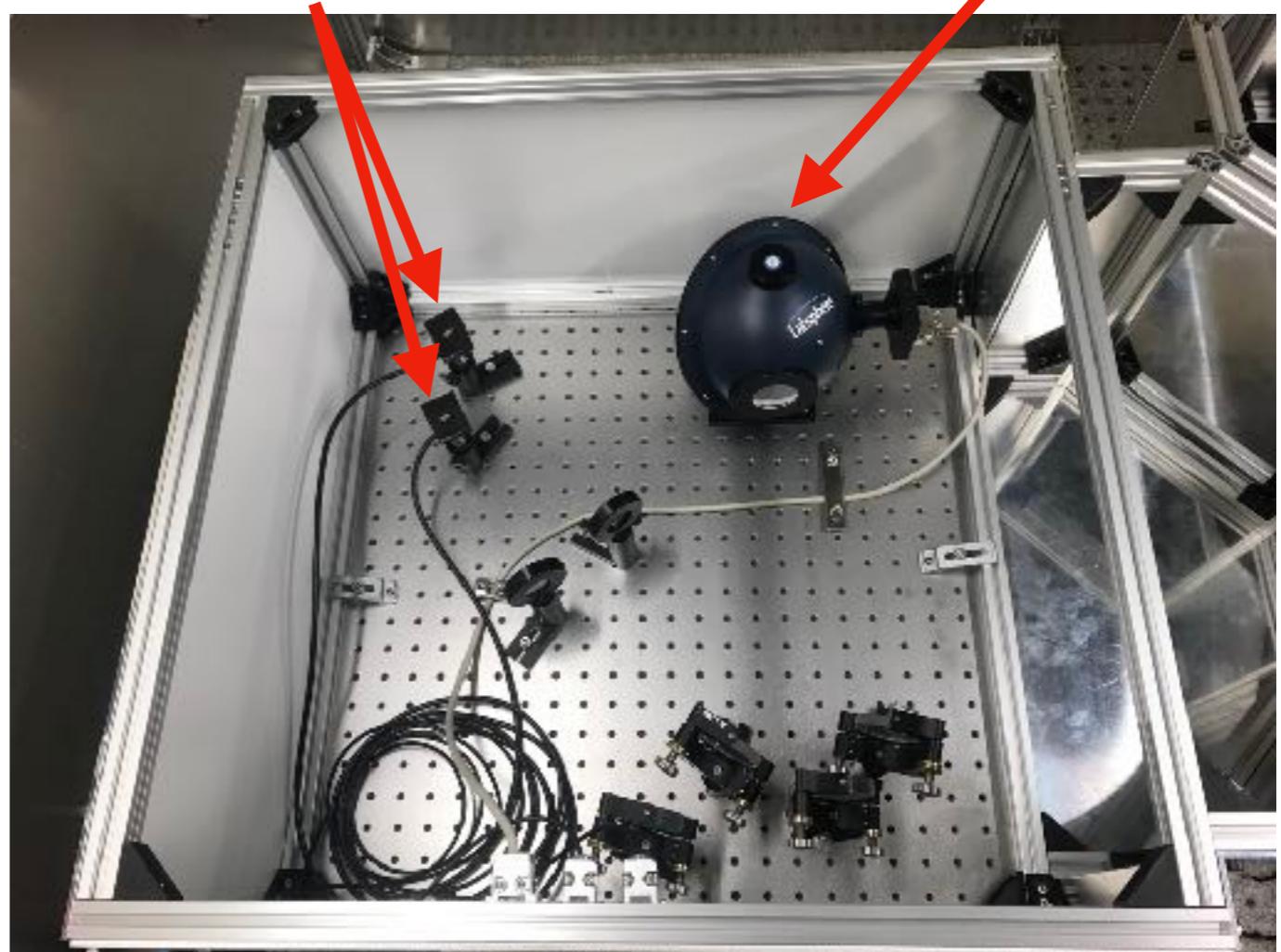
Transmitter Module



Receiver Module

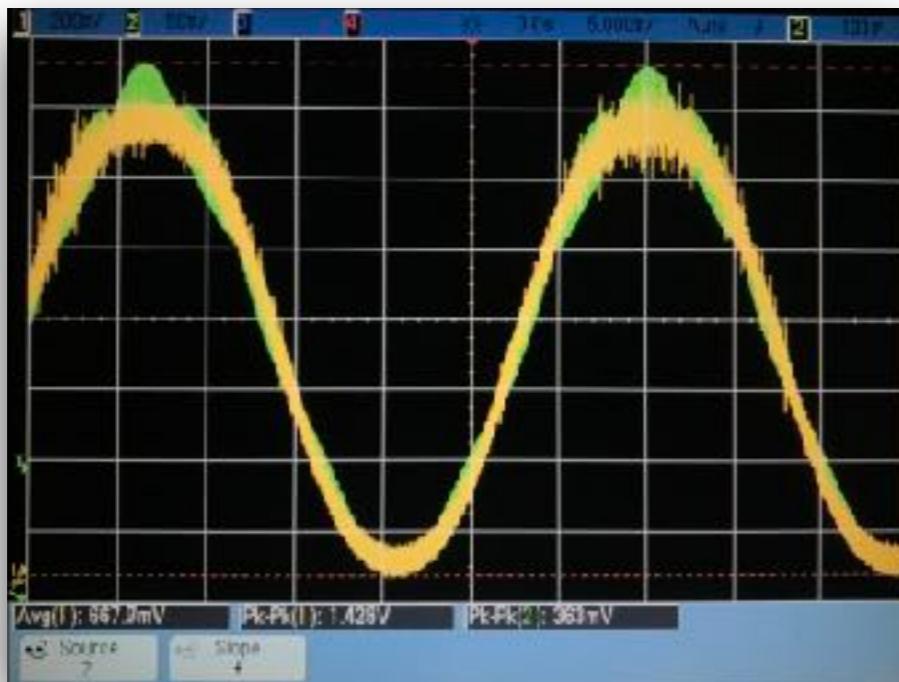


QPD
Quadrant
Photo Diode:
Monitoring the
beam position

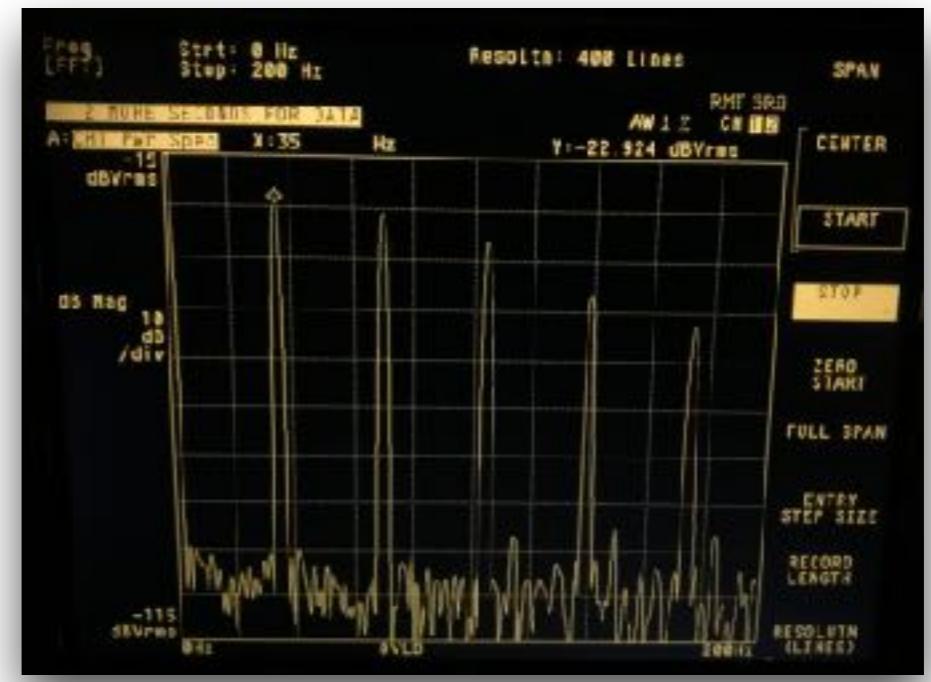


Requirements

Example of higher harmonics in 35Hz injection

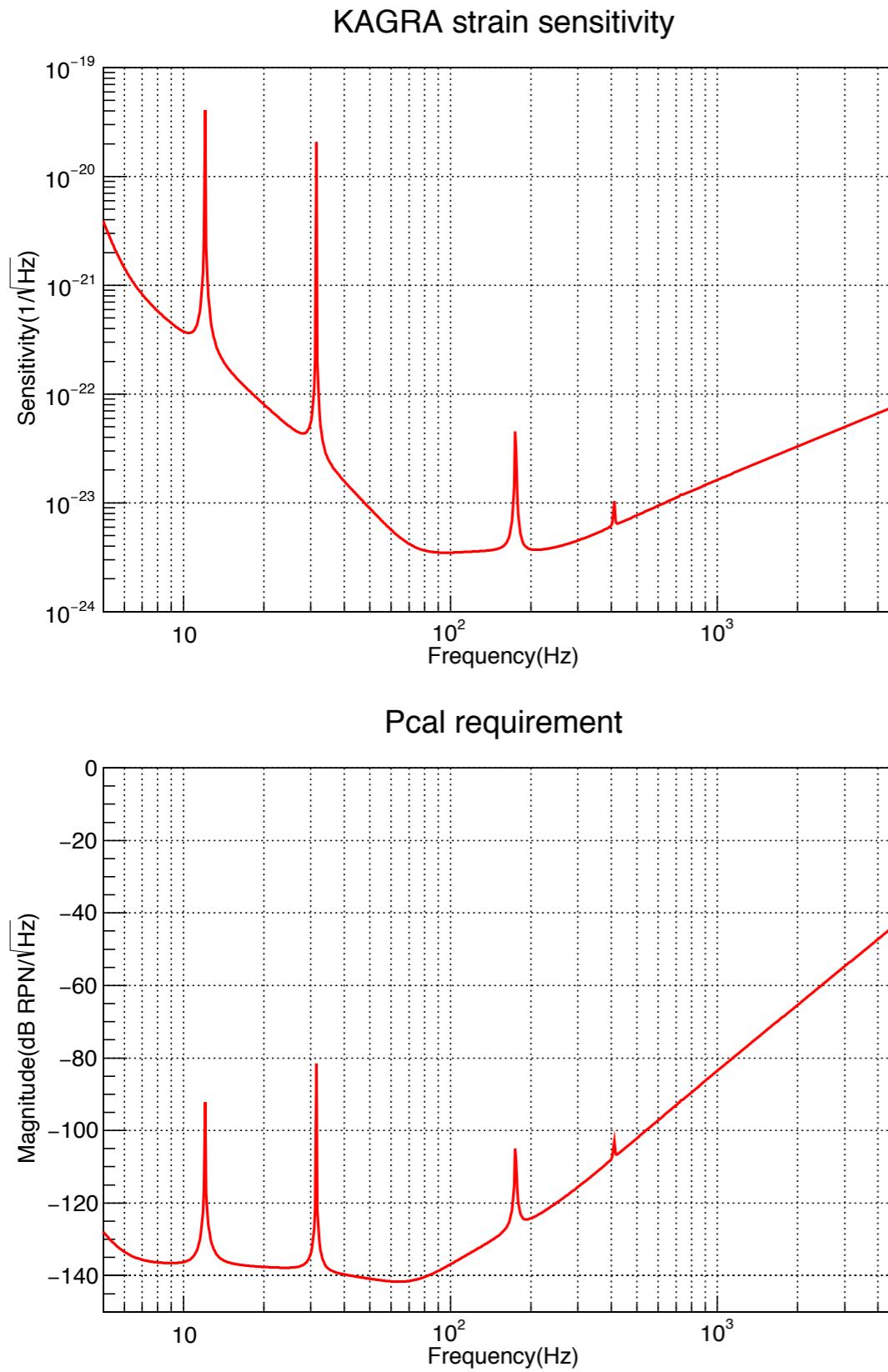


FFT
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To decide whether the peak is within requirements or not, first we need to define the noise requirement of Photon Calibrator.

Requirements



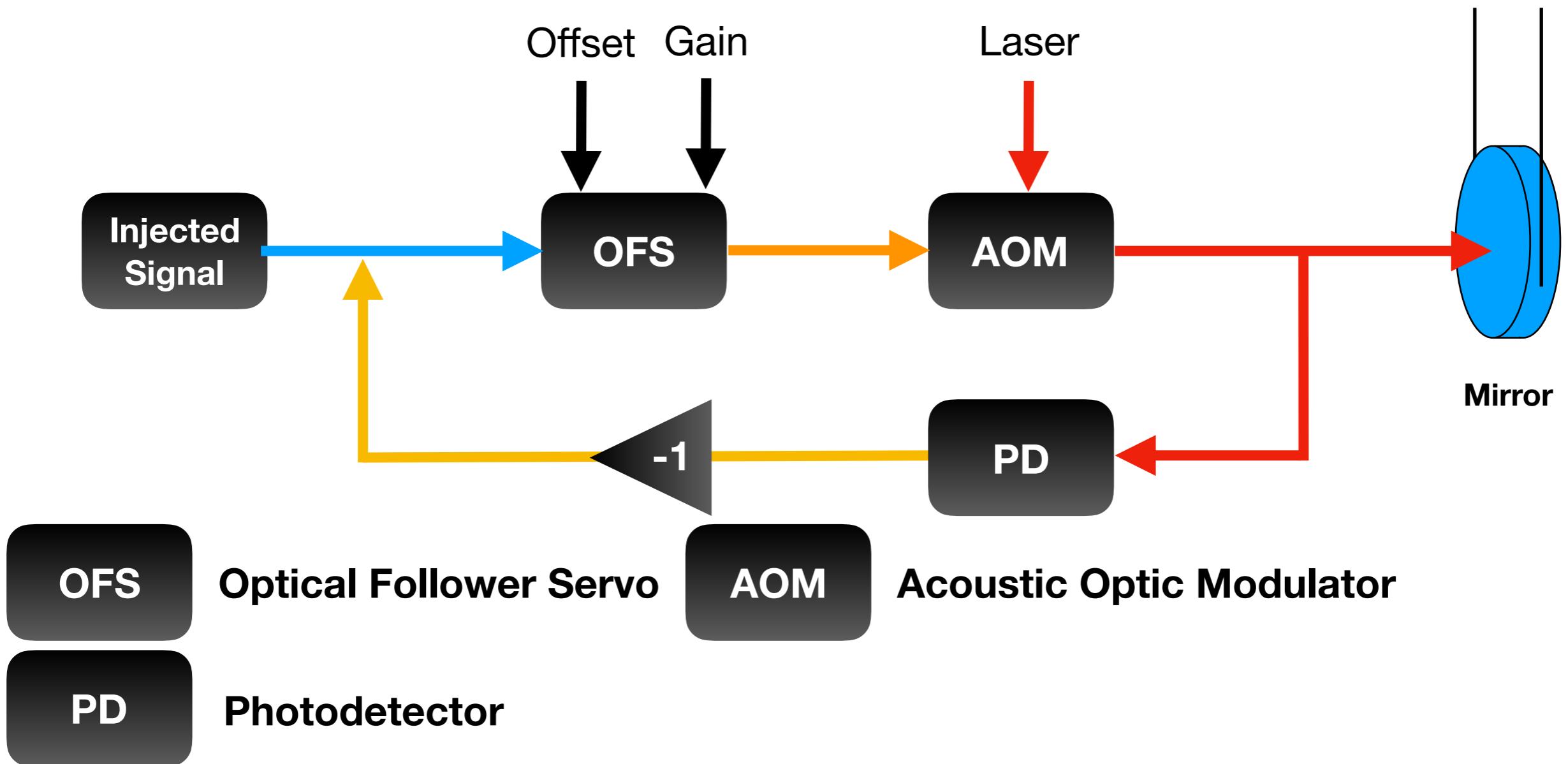
$$\Delta L(f) = \underbrace{\frac{2\Delta P \cos(\theta)}{c}}_{\text{Force}} \underbrace{\frac{1}{M(2\pi f)^2}}_{\text{Force to length transfer function}} < \frac{1}{10} \Delta h(f)L$$

strain sensitivity curve of KAGRA

$RPN = \frac{\Delta P}{P} = \frac{Mc(2\pi f)^2 \Delta h(f)L}{20P \cos(\theta)}$

M: ETM Mass (23kg)
 c: Speed of light
 L: Arm length of Interferometer (3km)
 P: Laser Power (10W)

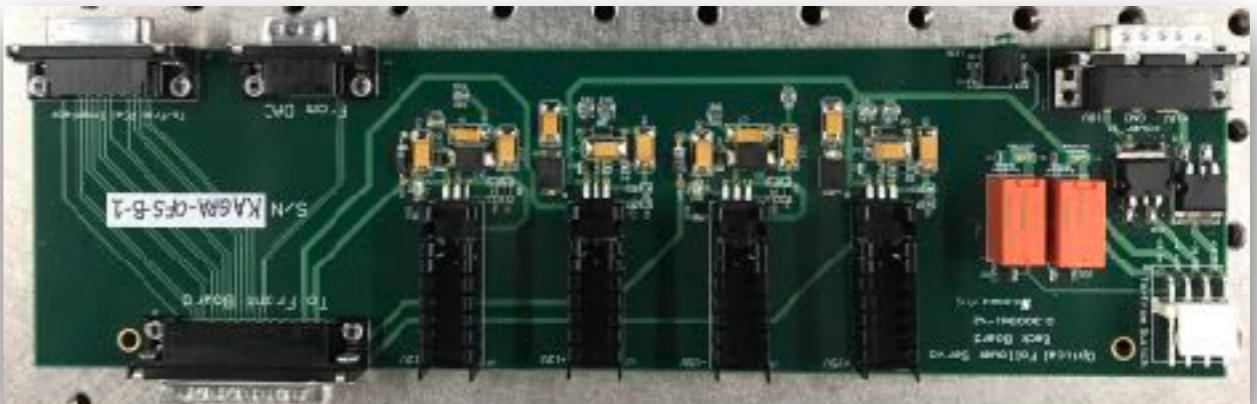
OFS feedback loop



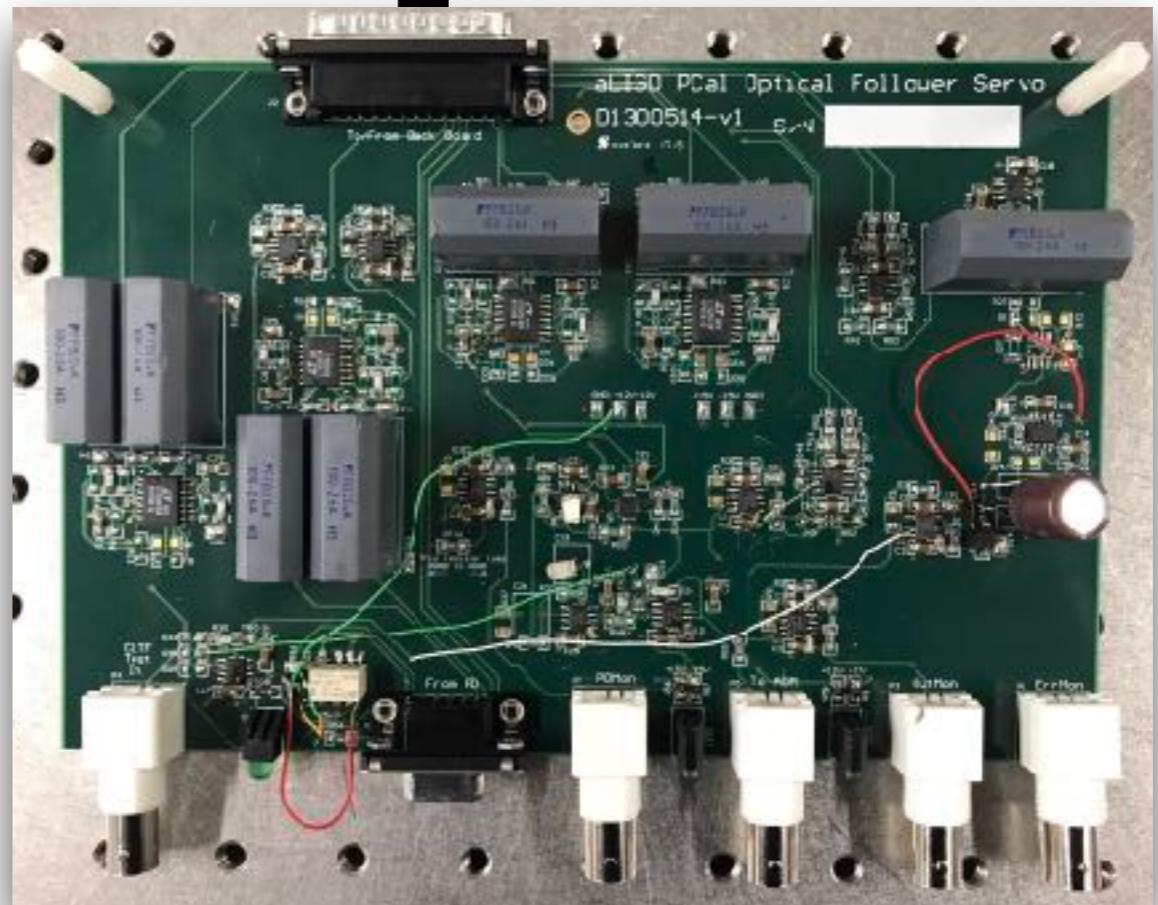
We use Optical Follower Servo and photodetector to make a closed-loop in order to reduce the noise of laser.

Optical Follower Servo

OFS Back Board
Ver. 1



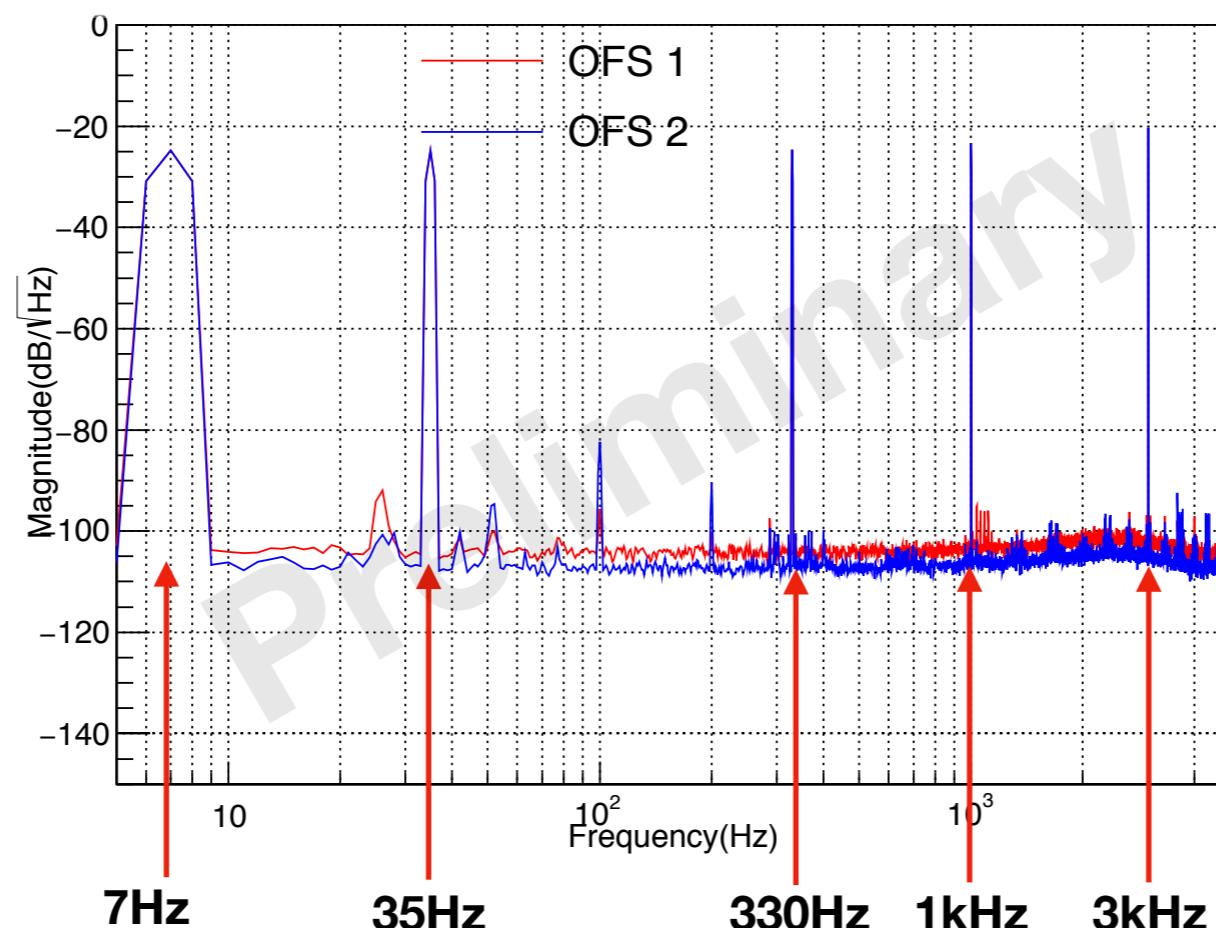
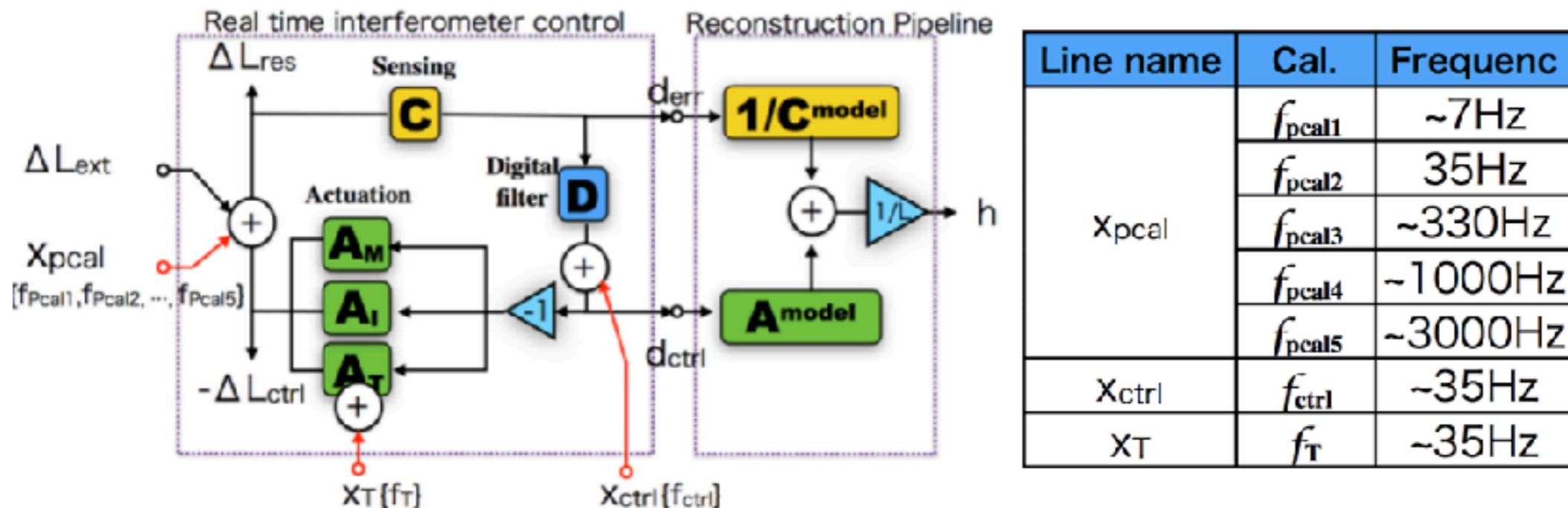
OFS Front Board
Ver. 4



OFS & Interface Chassis



Calibration Lines



Future Plan

Measurement of:

- Power spectrum
- Transfer function
- Higher Harmonic peaks
- Peak stability

Summary

- We built a Photon Calibrator with 20W laser for reconstructing gravitational wave.
- We used Optical Follower Servo to make a closed-loop feedback control.
- We plan to inject calibration line to understand the parameters in the real-time interferometer control.

